

# 3D-Fractography in Bending-Torsion Fatigue

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**ABSTRACT.** *A stereophotogrammetrical analysis in SEM is used to investigate the fracture morphology of the high-strength low-alloy steel generated under combined bending-torsion fatigue loading. Changes in many roughness parameters are presented for two series of profiles parallel and perpendicular to the local crack propagation direction in dependence on both the fatigue life and the loading ratio  $r = \tau_a / (\tau_a + \sigma_a)$  ( $\sigma_a$  is the bending amplitude and  $\tau_a$  is the torsion amplitude). Profile's fractal parameters are also calculated as "scale-independent" characteristics. Statistical distributions of facet angles with respect to the horizontal plane revealed prevailing orientations of local crack growth directions in various mixed-mode loading cases. One of the interesting results is that many roughness parameters start to increase rapidly above a critical value of loading ratio  $r_c \approx 0.5$ .*

## INTRODUCTION

Quantitative fractography has been used as a tool in materials research since the fracture surface can be considered to be a measure of the degradation process [1-7]. The surface roughness is usually extremely enhanced when a high portion of lower to medium amplitudes of shear loading modes II and III is applied [3]. In such cases the crack usually propagates in extremely complicated manner making local arrests and forming a branch/twist morphology or so-called factory roofs [1-4]. In the contrary a high amount of opening loading mode I or, sometimes, a high-amplitude of shear loading lead to a macroscopically flat surface.

The efforts to approach fractography in a more quantitative way has led to many interesting studies on the interconnection between the surface morphology and loading (or environmental) conditions [5-16]. However, the most crucial problem in the quantitative fractography remains to be a significant lack of experimental data from fracture surfaces created by biaxial loading [9]. This paper deals with several types of roughness parameters characterising the morphology variation produced by a combined bending-torsion loading.

## EXPERIMENTAL PROCEDURE

### *Fatigue Experiments*

Fatigue experiments were performed using the resonance testing machine MZGS-100. Five smooth specimens of high-strength low-alloy steel (yield stress  $R_e = 805$  MPa and ultimate stress  $R_m = 930$ MPa) were loaded until a final failure. Bending and torsion loadings (frequency 29 Hz,  $R = -1$ ) and their synchronous in-phase combinations were applied at room temperature. Loading settings and achieved fatigue life data are collected in Tab. 1, where  $\sigma_a$  is the bending amplitude,  $\tau_a$  is the torsion amplitude,  $r$  is the loading ratio,  $r = \tau_a / (\tau_a + \sigma_a)$ , and  $N_f$  is the number of cycles to failure. The fatigue life  $N_f$  of investigated specimens was in the order of  $10^6$  cycles (high cycle fatigue).

Table 1. Experimental data

Type of loading	$\sigma_a$ [MPa]	$\tau_a$ [MPa]	$r$ [-]	$N_f$
Pure bending	620	0	0	1229000
Combined bending-torsion	550	200	0.23	1252000
Combined bending-torsion	330	330	0.5	1099100
Combined bending-torsion	140	385	0.73	1700150
Pure torsion	0	390	1	4475000

### *Stereophotogrammetrical Reconstruction of Fracture Surface*

Stereogrammetry is based on the software evaluation of two digitalized images of fracture surface taken from different positions of view [15]. Stereoidimages of selected parts of fracture surface on each specimen were acquired using the scanning electron microscope Leo S440 and the tilting angle of stereopairs was  $10^\circ$ . The commercial software MeX was used for data processing. The output of the procedure is the digital elevation model of the depicted surface region consisting of up to 30.000 nonequidistantly localised points.

### *Profile and Fractal Parameters*

In order to evaluate different aspect of roughness, several types of parameters were adapted. Profile amplitude parameters depending only on changes in vertical  $z$ -coordinate are represented by the vertical profile range  $R_z$ , which is simply given as a difference between the highest and the lowest points of the profile, and the arithmetic roughness  $R_a$ , also known as a centre line average. The arithmetic roughness is defined as

$$R_a = \frac{1}{N} \sum_{i=1}^N |z_i - z_M|, \quad (1)$$

where  $N$  is a number of valid data points and  $z_M$  is the mean height value. Hybrid parameters affected by both the amplitude and the spacing of asperities are represented

by the linear roughness  $R_L$  [11]. It is defined as a ratio of the true profile length  $L$  and its projected length  $L_p$ :

$$R_L = \frac{L}{L_p} . \quad (2)$$

The other hybrid parameter is the vertical roughness  $R_V$ :

$$R_V = \frac{h}{L_p}, \quad (3)$$

where  $h$  is the sum of height differences between adjacent profile points.

A self-similarity of fracture morphology can be quantified by its fractal dimension  $D$ . Since different experimental techniques lead to different estimated values of fractal dimensions for real, quasi-similar, fracture profiles [17-19], two different fractal methods were taken into account. The box counting method is based on the following equation:

$$N(\eta) \propto \eta^{-D_B}, \quad (4)$$

where  $D_B$  is the box counting fractal dimension. The plane in which a curve is plotted is divided into squares of the side length  $\eta$ , and the number of squares  $N$  intersecting the curve is counted. The second algorithm was based on the divider method. The measured length dependence on the measurement unit  $\eta$  can be expressed as

$$L(\eta) \propto \eta^{-(D_D-1)}, \quad (5)$$

where  $D_D$  is the divider fractal dimension.

### ***Analysed Profiles***

For each specimen the square area of size 0.16 mm<sup>2</sup> was chosen with its centre at the distance of 0.76 mm from the crack initiation site located on the specimen surface. Using Delaunay triangulation [20-21], two sets of 50 profiles were traced for all analysed areas. In order to evaluate different position of the progressing macrocrack front, the first set laid in the crack propagation direction and the second one perpendicular to this direction.

## **RESULTS AND DISCUSSION**

In all presented Figures, curves for particular specimen are labelled by values of the loading ratio  $r$ . Parameter  $R_z$  calculated for profiles parallel and perpendicular to the

crack propagation direction is plotted in Fig. 1. Significantly higher values  $R_z$  in both directions correspond to specimens with the loading ratio higher than 0.5. Results for  $R_a$  in Fig. 2 show similar behaviour. Values of both the vertical range and the arithmetic roughness are somewhat higher for profiles taken in the direction parallel to the crack growth. Results for the linear roughness  $R_L$  and the vertical roughness  $R_V$  are shown in

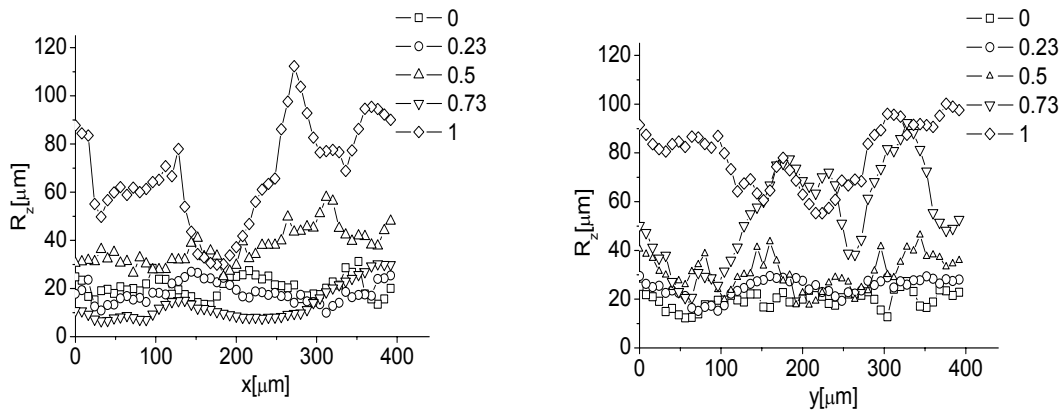


Figure 1. The vertical range  $R_z$  of profiles parallel (x-axis) and perpendicular (y-axis) to the local crack propagation direction.

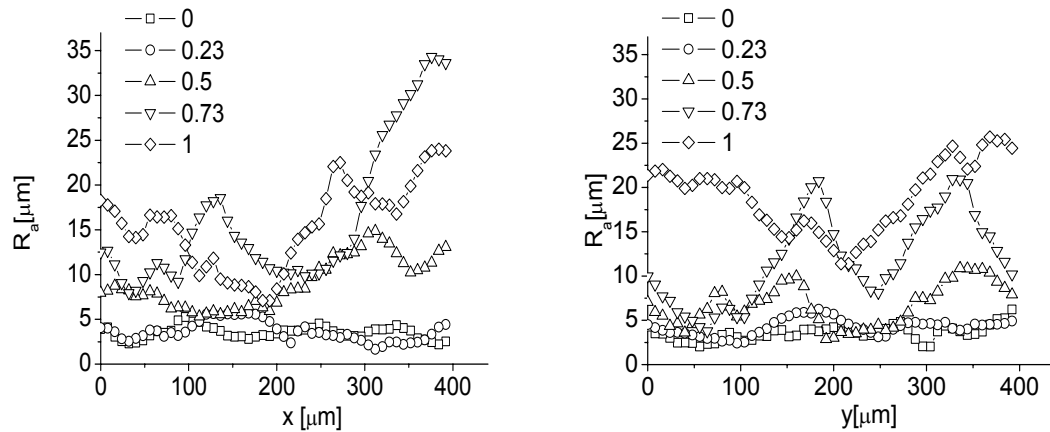


Figure 2. The arithmetic roughness  $R_a$  of profiles parallel (x-axis) and perpendicular (y-axis) to the local crack propagation direction.

Figs. 3 and 4. For both directions, again, the highest values are achieved for the pure torsion and the lowest  $R_L$  and  $R_V$  are detected for the pure bending. The dependence of the mean values of  $R_L$  and  $R_a$  on the ratio  $r$  in the direction parallel to the local crack propagation is plotted in Fig. 5. A step increase of both parameters starts closely before

reaching the value  $r = 0.5$ , in agreement with results reported for the low-cycle fatigue region [22]. Figs. 6 and 7 show fractal dimensions  $D_D$  and  $D_B$ . There is no significant

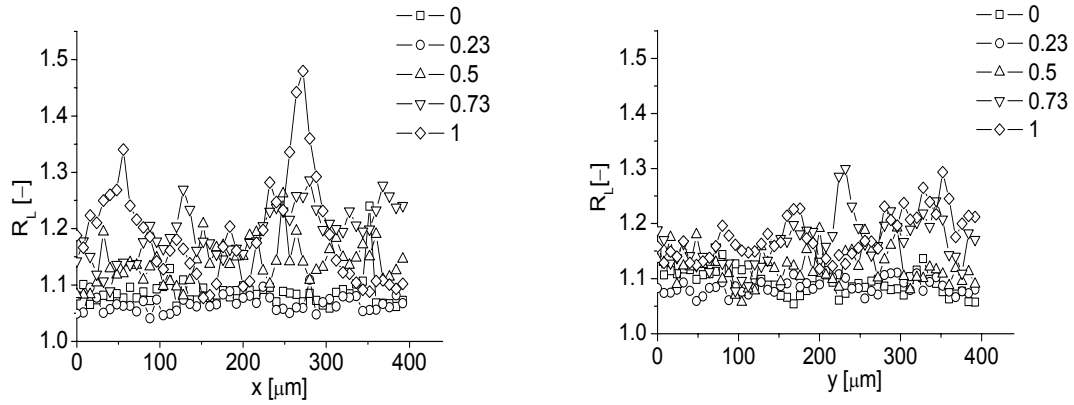


Figure 3. The linear roughness  $R_L$  of profiles parallel (x-axis) and perpendicular (y-axis) to the local crack propagation direction.

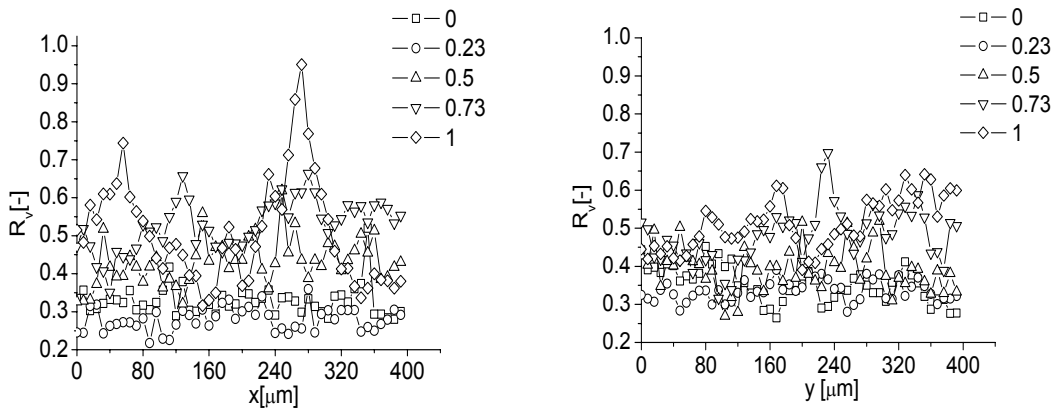


Figure 4. The vertical roughness  $R_V$  of profiles parallel (x-axis) and perpendicular (y-axis) to the local crack propagation direction.

relation between  $r$  and  $D_D$  or  $D_B$ . Values of both fractal dimensions strongly differ,  $D_B$  is changing in the range of 0.96-1.18 and  $D_D$  in the range of 1.03-1.08. Therefore, the method used for determination of the fractal dimension seems to be very important and should be always presented.

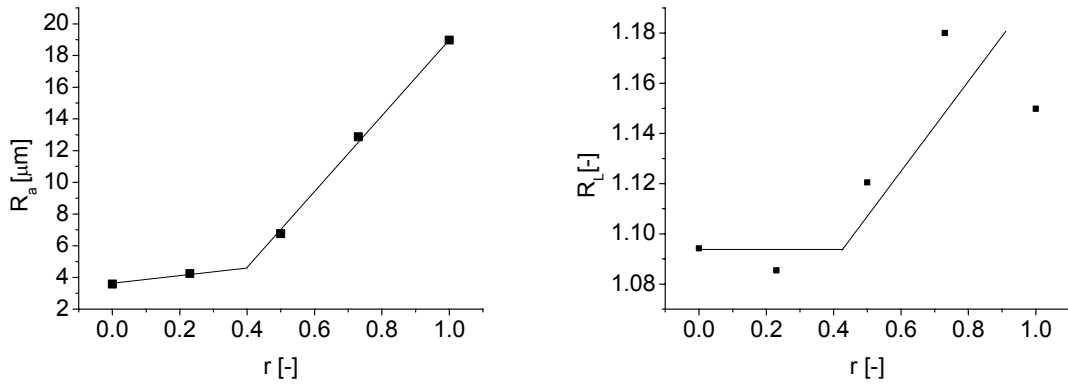


Figure 5. The dependence of roughness parameters on the loading ratio.

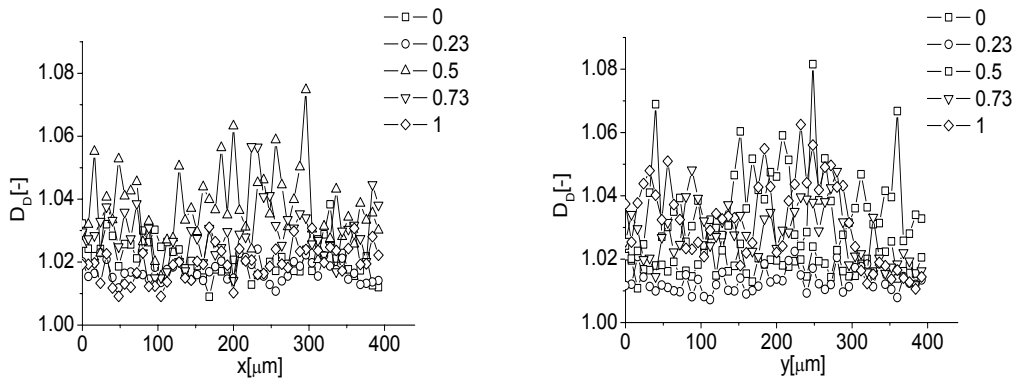


Figure 6. The fractal dimension  $D_D$  of parallel and perpendicular profiles.

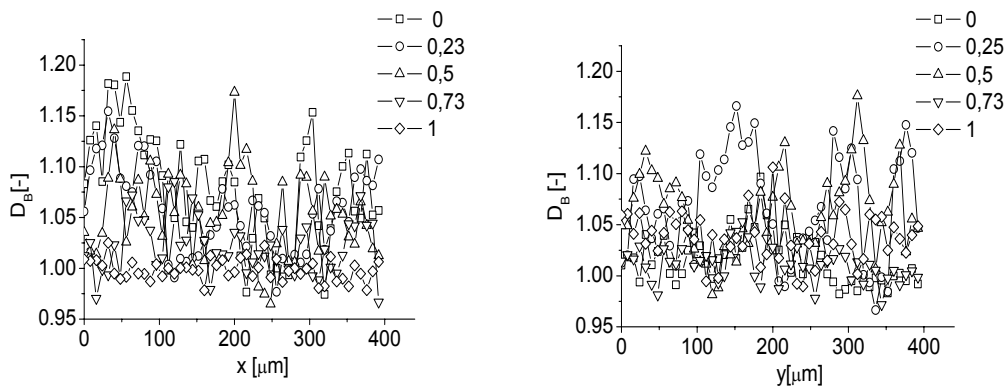


Figure 7. The fractal dimension  $D_B$  of parallel and perpendicular profiles.

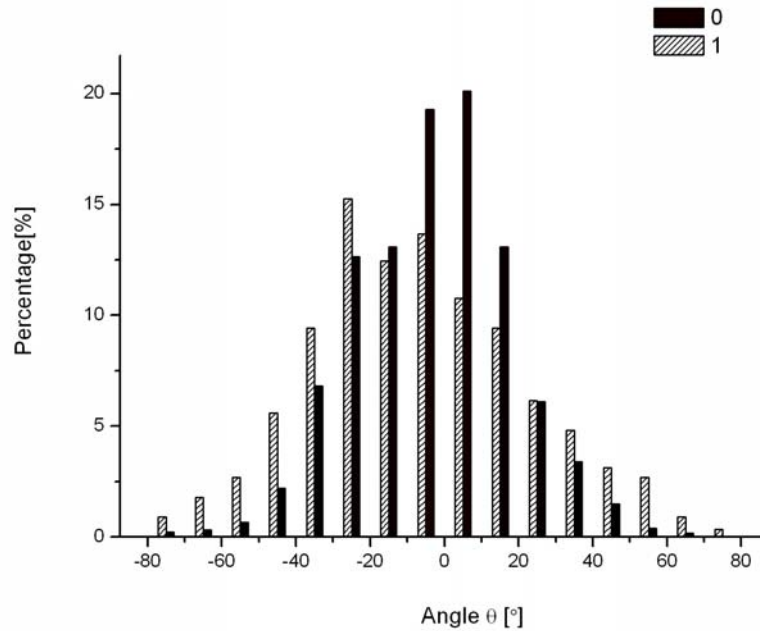


Figure 8. The angular distribution of facets for loading ratios  $r = 0$  (pure bending) and  $r = 1$  (pure torsion).

The histograms of the angular distribution for pure bending and pure torsion are shown in Fig. 8. In case of torsion, the angles higher than  $40^\circ$  (or lower than  $-40^\circ$ ) occur more frequently than in case of bending. On the contrary, the low angles within the range of  $-20^\circ$  to  $20^\circ$  are preferred on the fracture surfaces produced by bending.

## CONCLUSION

The most important results can be summarized in the following points:

- (i) Roughness parameters  $R_z$ ,  $R_a$ ,  $R_L$ ,  $R_v$  significantly increase above a critical value  $r_c \approx 0.5$  (the torsion loading component is equal to the bending one).
- (ii) In case of pure torsion angles higher than  $40^\circ$  (or lower than  $-40^\circ$ ) occur more frequently than in case of pure bending. The contrary holds for the low angles within the range of  $-20^\circ$  to  $20^\circ$ .
- (iii) There is no significant relationship between fractal dimensions  $D_D$  and  $D_B$  and the ratio of loading components.

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