

THE EFFECT OF THE NUMBER OF DEFORMATION MODES ON THE
DUCTILE-BRITTLE TRANSITION CRITERION IN SOLIDSE. SMITH¹ AND P.J. WORTHINGTON²ABSTRACT

A necessary condition for the deformation of a polycrystalline solid without the formation of cracks is that the grains can undergo a general strain; for this to be possible, five independent slip systems are required. Even when more than this limiting number are available, the material can still be brittle, but recent theories of the ductile-brittle transition in such a situation have not taken into account the number of available slip systems. An analysis has therefore been undertaken of the effect of the number of slip systems on the ductile-brittle transition criterion, and the results compared with those obtained from the earlier theories. It is shown that, in some situations, the value of the fracture surface energy obtained from the transition criterion may be modified considerably.

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INTRODUCTION

It is usually assumed⁽¹⁾ that a necessary condition for the motion of a polycrystalline solid without the formation of cracks is that the grains can undergo a general strain. If this strain is to be produced by slip, then five independent slip systems are required⁽²⁾; thus as a general rule it is found that when five independent systems are not available, then cracks are formed during the plastic deformation of a polycrystalline material. However, it is well known that in some cases even if the slip systems are available, the material can be brittle and the face-centred cubic structure is a very important example. Theories of the ductile-brittle transition in such situations have been put forward notably by Stroh, Cottrell and Petch⁽³⁻⁸⁾, particular notice being paid to the behaviour of mild steel. These theories do not take into account the number of available slip systems, as pointed out by Meakin and Petch⁽⁹⁾, who however point out that an increase in the number of systems will increase the probability of brittle fracture. Accordingly as part of a general theoretical investigation of the way in which crystal orientation and preferred slip systems affect the mechanical properties of solids, an analysis has been undertaken (Section 2) of the effect of the number of slip systems on the ductile-brittle transition criterion in solids.

THEORETICAL ANALYSIS

2.1. The Lower Yield Stress Theory of Armstrong et al⁽¹⁰⁾

Theories of the ductile-brittle transition in solids are generally related to those of the lower yield stress σ of polycrystalline materials, and it is well known that this obeys the relationship:

$$\sigma = \sigma_0 + k l^{-1/2} \dots \dots \dots (1)$$

where l is the grain diameter, σ_0 and k being constants for a given set of testing conditions. Early theories^(6,11,12) of the lower yield stress were based on a model, whereby the spread of plasticity at the lower yield point occurred by the concentrated shear stress of a slip band in one grain initiating slip in a neighbouring grain.

It was assumed that in every grain the slip plane and slip direction both made an angle of 45° with the applied tensile stress, and the effects of the number of slip systems and the differing orientations of the crystals which form a polycrystalline aggregate were neglected. However, Armstrong et al⁽¹⁰⁾ have extended the theory to the case of a random polycrystalline aggregate by using an averaging procedure, and Wilson and Chapman⁽¹³⁾ and Smith and Worthington⁽¹⁴⁾ have considered the case where some degree of preferred orientation is present.

Armstrong et al assumed that plasticity spreads by a slip band

in one grain operating a dislocation source in the next grain at a distance r directly ahead of the band. The shear stress at such a point is:

$$(\tau - \tau_i) (1/4r)^{1/2} \dots \dots \dots (2)$$

acting on a plane parallel to the original band and in a direction parallel to the original slip direction⁽¹⁵⁾, where τ is the applied shear stress acting on the band and τ_i is the shear stress opposing the motion of an unlocked dislocation in the band. Since the orientation of the grains are random, on the average, yielding will propagate when (2) reaches the average shear stress for initiation of slip. If τ_c is the critical resolved shear stress for this process, then on average yield will propagate when

$$(\tau - \tau_i) (1/4r)^{1/2} = m\tau_c/2 \dots \dots \dots (3)$$

or

$$\tau = \tau_i + m\tau_c r^{1/2} l^{-1/2} \dots \dots \dots (4)$$

where m is an average orientation factor. To obtain m , we simply average m_f for a collection of randomly oriented free crystals, where m_f relates the axial tensile stress σ_s applied to a single crystal to the shear stress τ_s on the most favourably oriented slip plane by $\sigma_s = m_f \tau_s$. For simplicity, we restrict ourselves to this Sachs⁽¹⁶⁾ average which gives the condition for operation of a single source and do not use the Taylor⁽¹⁷⁾ average, which allows for deformation on less favourably oriented planes to maintain continuity. The tensile yield stress will be $m\tau$, the average over the randomly oriented polycrystalline aggregate, i.e.

$$\sigma = m\tau_i + m^2 \tau_c r^{1/2} l^{-1/2} \dots \dots \dots (5)$$

Hence, when interpreting experimental results by relation (1), σ_0 is associated with $m\tau_i$ and k with $m^2 \tau_c r^{1/2}$.

If $m = 2$, the model becomes that considered by Petch⁽¹¹⁾ and Codd and Petch⁽¹²⁾, where in every grain the slip plane and direction both make an angle of 45° with the applied tensile stress. Relation (5) then reduces to

$$\sigma = 2\tau_i + 4\tau_c r^{1/2} l^{-1/2} \dots \dots \dots (6)$$

when, in the interpretation of experimental results by relation (1), σ_0 is associated with $2\tau_i$ and k with $4\tau_c r^{1/2}$. In recent years, when discussing experimental results on polycrystalline body-centred and face-centred cubic metals and alloys, most workers have used this simple interpretation of σ_0 and k when considering for example the effects of temperature, strain rate and alloy composition. However, as will be indicated later, this can lead to difficulties when considering the ductile-brittle transition criterion.

continuity. A more general situation in body-centred cubic structures is when slip occurs on any plane provided the slip direction is always $\langle 111 \rangle$, as in 3% silicon iron at room temperature⁽²⁷⁾; in such a situation as this, m should not be much greater than 2 and the value 2.4 has been obtained experimentally⁽²⁸⁾. With such a value for m , II/I in relation (11) will be less than 20% if $\sigma_0 < kl^{-2}$ and this will be the case for a conventional mild steel having a fine grain size ($l \sim 0.01$ mm) when tested around the transition temperature ($\sim -196^\circ\text{C}$). Even for a steel with a coarse grain size ($l \sim 0.2$ mm), II/I should not be greater than about 50%. Thus in the case of mild steel, for which the earlier theories were primarily developed, the simple fracture criterion (9) is probably adequate; consideration of the second term (II) in the modified criterion (10) will only give slightly greater values of γ .

However, as seen by inspection of (11), the effect of the differing orientations of the grains which form a polycrystalline aggregate will be important (i.e. II becomes large) when $\sigma_0 \gg kl^{-2}$. Such a situation exists in many of the transition metals^(29,30); σ_0/kl^{-2} can typically be 10 or more even for a fine grain material. Then II/I in relation (11) will be almost 2 (taking $m = 2.4$) and can be even higher for coarse grain size material. Values of γ obtained from a consideration of the simple relation (9) will then be far too low. In the extreme case when $\sigma_0 \gg kl^{-2}$, criterion (10) reduces to

$$\frac{m(m-2)\tau_i^2 l}{4\mu} = \gamma \dots\dots\dots (12)$$

Thus low values of τ_i , the lattice friction stress, l , the grain size and m (i.e. a high multiplicity of deformation modes) are all conducive to ductility.

This discussion has so far been based on slip processes being responsible for crack formation; as indicated earlier, however, it appears that in some situations cracks can be formed as a result of mechanical twinning, the detailed mechanisms having been reviewed by Hull⁽³¹⁾. We now examine how the ductile-brittle transition criterion is modified. There are two cases to discuss⁽³²⁾:

(a) Where the critical event in the fracture process is the growth of a crack which has been nucleated by twinning processes. In such cases twins are formed at stress levels lower than the fracture stress, but these levels are not high enough for the energetic condition for crack growth to be satisfied. Such situations are characterized by the presence of mechanical twins away from the fracture surfaces.

(b) Where the critical event in the fracture process is the onset of mechanical twinning. In such cases the energetic condition for crack growth is more than satisfied at the applied stress level required for twinning. Such situations are characterized by the

absence of mechanical twins away from the fracture surfaces.

For case (a), n_a in relation (7) should then be $[(\sigma/2 - \tau_i(tw)) l/\mu]$ where $\tau_i(tw)$ is the friction stress which opposes the motion of each twinning dislocation (except perhaps the leading one) from which a twin is formed. Unfortunately $\tau_i(tw)$ is a quantity about which very little is known, and thus alternatively n_a has been estimated by actually measuring twin thicknesses and using $n_a \sim t \tan \theta$ where t is the average twin thickness and θ is the angle of shear^(31,33). As pointed out elsewhere however⁽²⁸⁾, this procedure is not very satisfactory as one is measuring the thicknesses of twins which have had the opportunity to relax the local stresses near their tips by slip or more twinning; thus one obtains too large a value for the thickness of an unrelaxed twin, which is the important parameter in initiating fracture. Fortunately we do know, at least in the case of ferritic materials, that $\tau_i(tw)$ is smaller than τ_i for slip; thus proceeding to the extreme case and putting $\tau_i(tw)$ to be zero, the fracture criterion (7) becomes

$$\frac{\sigma^2 l}{4\mu} = \gamma \dots\dots\dots (13)$$

and in determining γ , the experimentally observed values for σ and l at the transition point can be used, without needing to know the value of m .

For case (b), it is necessary to examine the criterion for the onset of twinning. Experimental work^(28, 34-36) suggests that some localized slip is required to form a twin; and very approximately the stress for twinning can be expressed as

$$\sigma(tw) = 2\tau_i + k(tw)l^{-1/2} \dots\dots\dots (14)$$

Accordingly for fracture at the lower yield stress we have

$$2\tau_i + k(tw)l^{-1/2} = \sigma_0 + kl^{-2} \dots\dots (15)$$

or

$$\left(1 - \frac{2}{m}\right) \sigma_0 = [k(tw) - k]l^{-1/2} \dots\dots (16)$$

Of course in this case γ cannot be obtained from experimental measurements at the transition point, and we reach the general conclusion that only in the case of slip induced cleavage is it necessary to have a knowledge other than the experimentally measured values of σ_0 , k and l at the transition point in determining γ ; in this special case m must be known.

Finally, it is worth emphasizing that throughout this paper, whether slip or twinning causes fracture, it has been assumed as

indeed also in the original model⁽⁶⁾, that all the dislocations in the slip or twin band enter the crack and assist it to grow. This may not necessarily be the case, but an analysis allowing for this effect is beyond the scope of the present paper; in this context the present analysis will give an upper bound to values of γ obtained from the transition criterion. All one can do at this stage is to proceed empirically and let a proportion $\alpha (< 1)$ of the dislocations enter the crack. Then relation (10) becomes

$$\frac{\alpha \sigma k l^{\frac{1}{2}}}{4\mu} + \alpha \left(1 - \frac{2}{m} \right) \frac{\sigma \sigma_0 l}{4\mu} = \gamma \quad \dots \dots \dots (17)$$

ACKNOWLEDGMENT

The authors thank the Central Electricity Generating Board for permission to publish this paper. They also thank Drs. Johnston, Davies and Stoloff (Ford Motor Company Research Laboratory, Dearborn, Michigan, U.S.A.) for valuable correspondence on this subject.

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